# MC6N-ECAT EtherCAT Master

#### **INTRODUCTION**

The MC6N is a high performance Motion Coordinator which perfectly dialogues with the R.T.A. motion control solution (AC servos and steppers).

# **HIGHLIGHTS**

- High performance motion coordinator for remote servo and stepper drives via EtherCAT bus.
- EtherCAT amplifiers can be connected and driven in cyclic synchronous position, speed or torque modes.
- 1 GHz dual core processor controlling up to 64 axes (twice as the previous model MC4N).
- Same simple programming as the traditional analog axes, with the possibility to set up drives and process alarms over the EtherCAT bus.
- Ideal for high axes count machines or robotic applications.

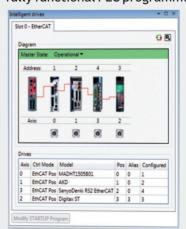


#### 1st GENERATION (Vs) **2nd GENERATION** MC4N MC6N 1GHz dual core ARM ■ 532 Mhz ARM11 Cortex-A7 processor up to 32 axes up to 64 axes Execution time: Execution time: 35 lines/ms 102 lines m/s 350 mA power 180 mA power consumption consumption Maximum retentive Maximum retentive variable 4096 variable 16384 Profinet I/O: no Profinet I/O: yes

## **EASY PROGRAMMING SYSTEM**

The built-in Ethernet port allows programming and connection of common PLC and HMI protocols.

Standard IEC 61131-3 languages available, allowing a fully functional PLC programming system.

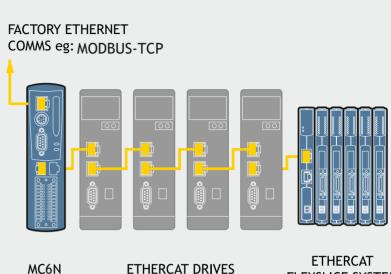






# **SPECIFICATIONS**

- Up to 64 EtherCAT digital drive axes virtual axes
- Up to 1024 Ether CAT I/O
- Ethercat cycle times down to 125 μsec.
- Linear, circular, helical and spherical interpolation
- EnDAT and SSI absolute encoder supported
- Ethernet-IP / Modbus TCP / Trio Activex /HMI Uniplay / UDP / Ethernet interface built-in
- Metal backplate for maximum noiselessness.
- Robotic transformations
- High speed registration inputs
- SD memory card slot
- CANopen I/O expansions
- RoHS, UL and CE approved



ETHERCAT DRIVES

FLEXSLICE SYSTEM



## **MECHANICAL DIMENSIONS**

